Adam and I will be creating a vehicle that will include two light sensors. One light sensor will be used as sonar for determining certain light or darkness to make the vehicle stop. Also it will be programed so that when the vehicle approaches an object or a hand is put over it, the vehicle will stop. The second light sensor will be used to follow a line until is it endangered by obstacle in its way. For building this vehicle, the light sensors might be difficult to position due to taping issues we may have. Also the light sensor may have issues due to reading light values. The wiring part of this should not be that bad because of past experience that we both have had.